

Redshift space distortion and halo velocity bias

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Zheng, Yong, Oh, et al., 2015, in preparation

Zhang, Zheng & Jing, 2014, arXiv: 1405.7125, PRD accepted

Zheng, Zhang & Jing, 2014a, arXiv: 1409.6809, PRD accepted

Zheng, Zhang & Jing, 2014b, arXiv: 1410.1256, PRD accepted

Outline

- Redshift space distortion
 - Key question: if the velocity dispersion σ_v^2 in the FoG term is scale independent or not?
 - Scoccimarro model
 - TNS model
- Halo velocity bias
 - Theoretical prediction from Gaussian statistics (k^2 scale dependence)
 - Measurement from simulation ($b_v = 1$ at $k \le 0.1 h/\text{Mpc}$ in 2% accuracy)

Real space: Redshift space: Introduction The redshift position **s**: 30 Squashing effect 20 Linear regime (Mpc/h) $\mathbf{s} = \mathbf{x} + v_z/(aH)\,\hat{\mathbf{z}}$ Collapsed -20 Turnaround -30 20 z=1Reid et al. 2012 Finger-of-god Collapsing 10 A. J. S. Hamilton, astro-ph/9708102 $\Delta f/f$ [%] 0 5-10% -10 model A + gaus. $D(\sigma_v)$ + NL-bias O(1%) model A + exp. $D(\sigma)$ + NL-bias Observationally: -20 model B + gaus. $D(\sigma_{c})$ + NL-bias model B + exp. $D(\sigma)$ + NL-bias Theoretically: model C + gaus. $D(\sigma_{v})$ + NL-bias ---- \triangle -----30 Nonlinear mapping model C + exp. $D(\sigma)$ + NL-bias Euclid, BigBOSS 0×10⁻² 8×10⁻² 6×10⁻² 4×10⁻² 2×10⁻² Nonlinear evolution Bias modelling et all: 11 13 15 17 19 r_{\perp}^{min} [h⁻¹ Mpc] Torre & Guzzo, 1202.5559

Phenomenological RSD model

$$P^{(S)}(k, \mu) = D_{FoG}[k\mu f \sigma_{v}] P_{Kaiser}(k, \mu),$$

$$\begin{split} P^{(\mathrm{S})}(k,\mu) &= D_{\mathrm{FoG}}[k\mu f\sigma_{\mathrm{v}}] P_{\mathrm{Kaiser}}(k,\mu), \\ P_{\mathrm{Kaiser}}(k,\mu) &= \begin{cases} (1+f\mu^2)^2 P_{\delta\delta}(k) & \text{linear,} \\ P_{\delta\delta}(k) + 2f\mu^2 P_{\delta\theta}(k) + f^2\mu^4 P_{\theta\theta}(k) & \text{nonlinear.} \end{cases} \end{split}$$

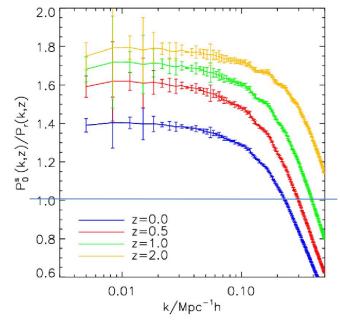
$$D_{\text{FoG}}[x] = \begin{cases} \exp(-x^2) & \text{Gaussian,} \\ 1/(1+x^2) & \text{Lorentzian.} \end{cases}$$

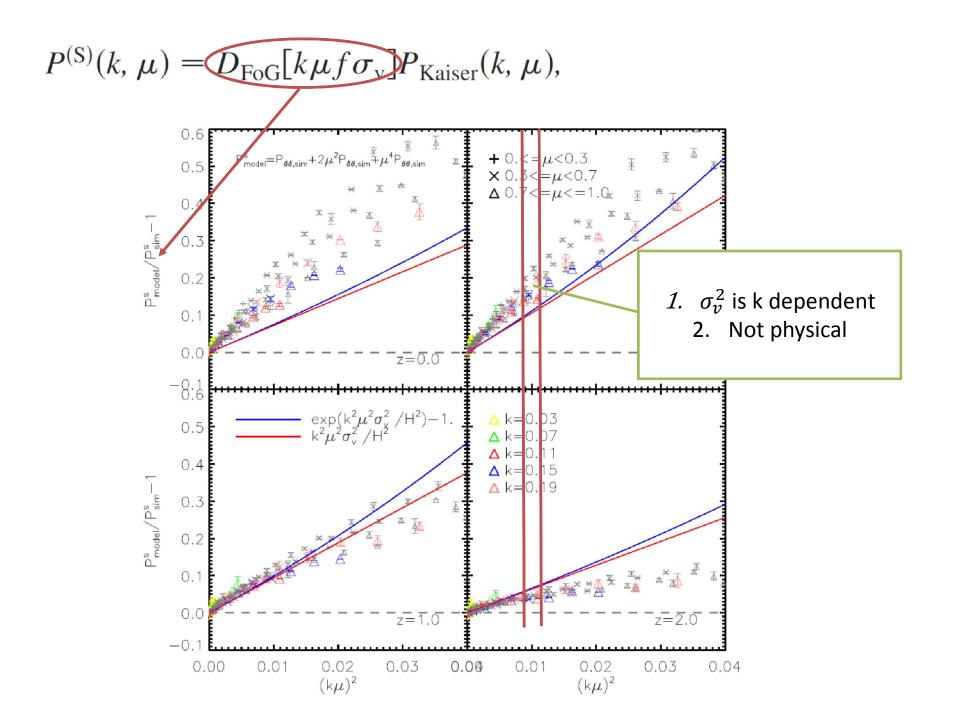
interpreted to be global (pairwise) velocity dispersion, a constant fitting parameter (?)

Taruya et al. arXiv:1006.0699

$$G(k\mu; \sigma_v) = \begin{cases} e^{-k^2 \mu^2 \sigma_v^2/2} & \text{Gaussian,} \\ \left(1 + k^2 \mu^2 \sigma_v^2/2\right)^{-2} & \text{Lorentzian.} \end{cases}$$

arXiv:1506.05814v1





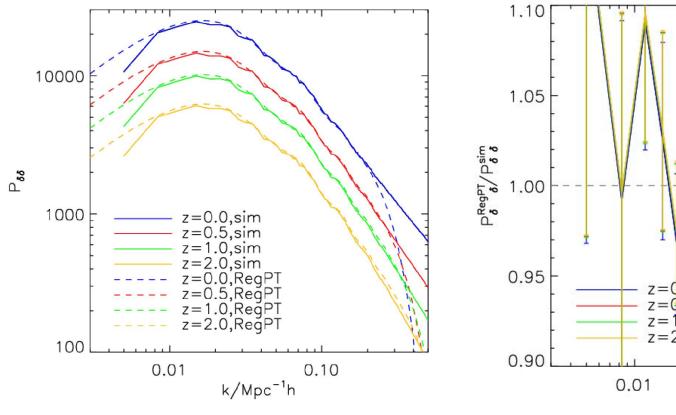
Mathematically show the point: scoccimarro's model

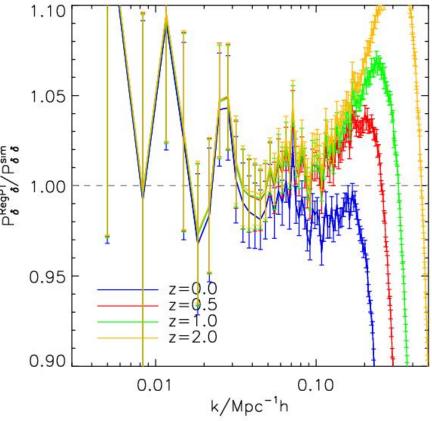
$$P_{\text{Kaiser}}(k, \mu) = \begin{cases} (1 + f\mu^2)^2 P_{\delta\delta}(k) & \text{linear,} \\ P_{\delta\delta}(k) + 2f\mu^2 P_{\delta\theta}(k) + f^2\mu^4 P_{\theta\theta}(k) & \text{nonlinear.} \end{cases}$$

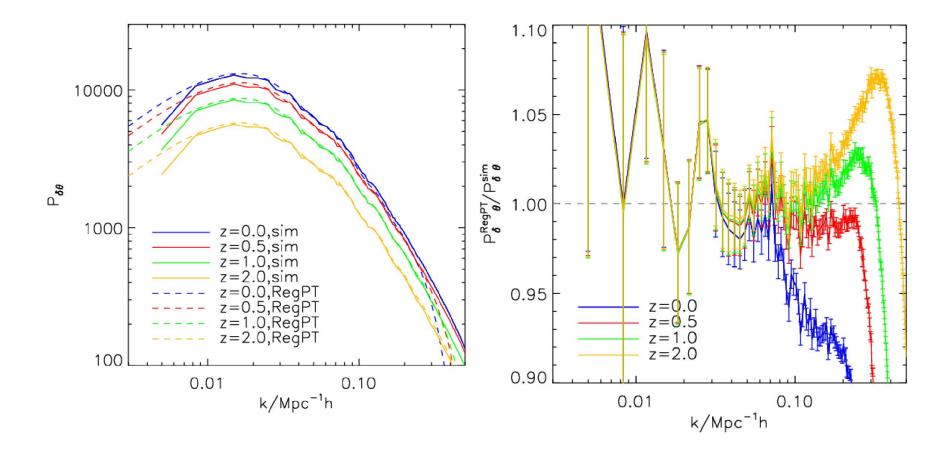
For each k bin, we restrict to $k\mu < 0.1$, and fit the σ_v^2 .

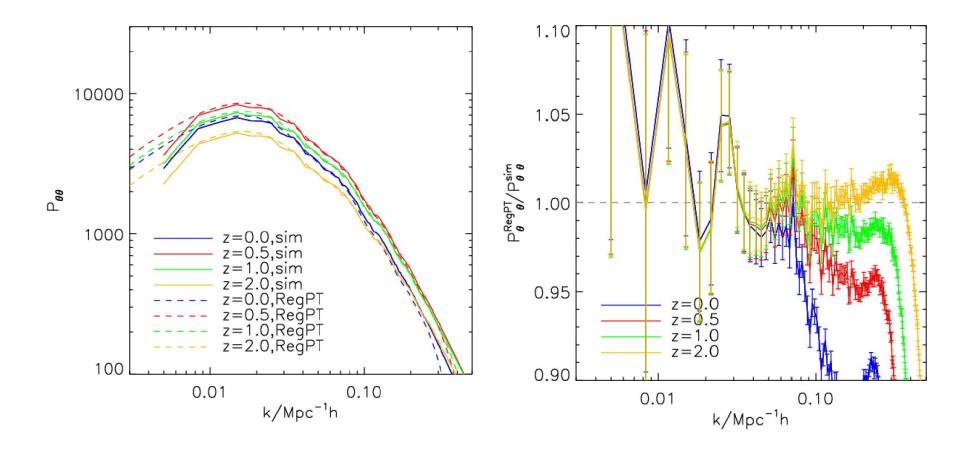
RegPT: Taruya et al. PHYSICAL REVIEW D 86, 103528

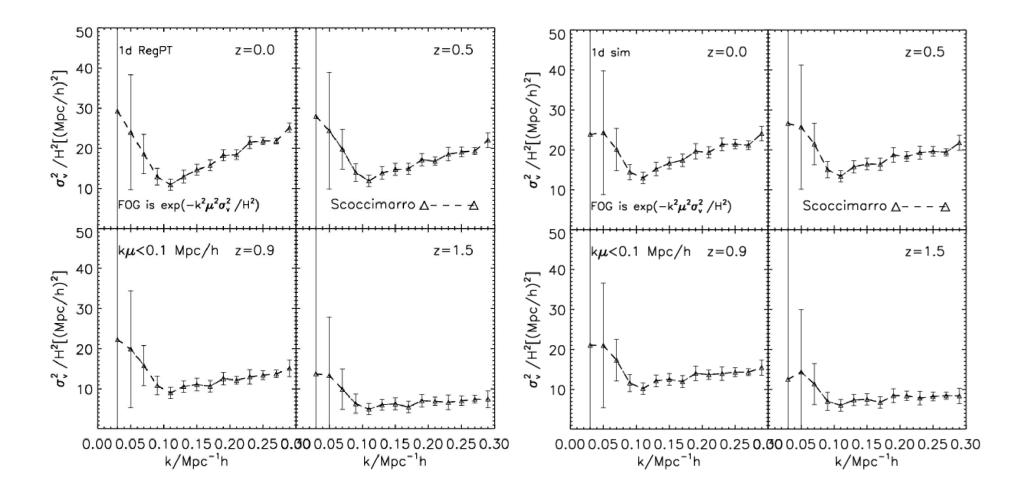
$$\begin{split} P_{ab}(k;\eta) &= \Gamma_{a,\mathrm{reg}}^{(1)}(k;\eta) \Gamma_{b,\mathrm{reg}}^{(1)}(k;\eta) P_0(k) + 2 \int \frac{d^3\boldsymbol{q}}{(2\pi)^3} \Gamma_{a,\mathrm{reg}}^{(2)}(\boldsymbol{q},\boldsymbol{k}-\boldsymbol{q};\eta) \Gamma_{b,\mathrm{reg}}^{(2)}(\boldsymbol{q},\boldsymbol{k}-\boldsymbol{q};\eta) P_0(q) P_0(|\boldsymbol{k}-\boldsymbol{q}|) \\ &+ 6 \int \frac{d^6\boldsymbol{p} d^3\boldsymbol{q}}{(2\pi)^6} \Gamma_{a,\mathrm{reg}}^{(3)}(\boldsymbol{p},\boldsymbol{q},\boldsymbol{k}-\boldsymbol{p}-\boldsymbol{q};\eta) \Gamma_{b,\mathrm{reg}}^{(3)}(\boldsymbol{p},\boldsymbol{q},\boldsymbol{k}-\boldsymbol{p}-\boldsymbol{q};\eta) P_0(p) P_0(q) P_0(|\boldsymbol{k}-\boldsymbol{p}-\boldsymbol{q}|) \end{split}$$











Taruya's model

$$P^{(S)}(k,\mu) = D_{FoG}[k\mu f \sigma_{V}] \{ P_{\delta\delta}(k) + 2f\mu^{2} P_{\delta\theta}(k) + f^{2}\mu^{4} P_{\theta\theta}(k) + A(k,\mu) + B(k,\mu) \}.$$

$$j_{1} = -ik\mu f, \qquad A_{1} = u_{z}(\mathbf{r}) - u_{z}(\mathbf{r}'),$$

$$A_{2} = \delta(\mathbf{r}) + f\nabla_{z}u_{z}(\mathbf{r}), \qquad A_{3} = \delta(\mathbf{r}') + f\nabla_{z}u_{z}(\mathbf{r}').$$

$$A(k,\mu) = j_{1} \int d^{3}\mathbf{x} e^{ik\cdot \mathbf{x}} \langle A_{1}A_{2}A_{3}\rangle_{c},$$

$$B(k,\mu) = j_{1}^{2} \int d^{3}\mathbf{x} e^{ik\cdot \mathbf{x}} \langle A_{1}A_{2}\rangle_{c} \langle A_{1}A_{3}\rangle_{c}.$$

Perturbation:

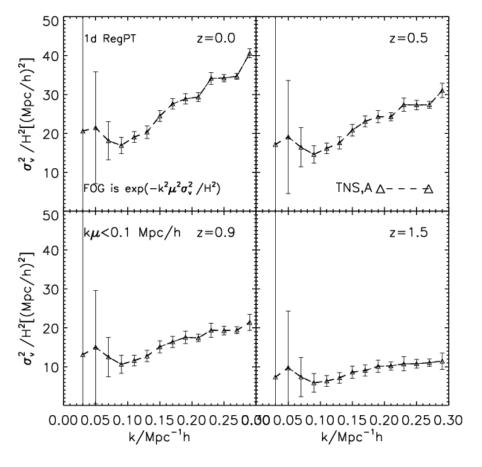
$$A(k, \mu) = (k\mu f) \int \frac{d^3 \mathbf{p}}{(2\pi)^3} \frac{p_z}{p^2} \{ B_{\sigma}(\mathbf{p}, \mathbf{k} - \mathbf{p}, -\mathbf{k}) - B_{\sigma}(\mathbf{p}, \mathbf{k}, -\mathbf{k} - \mathbf{p}) \},$$

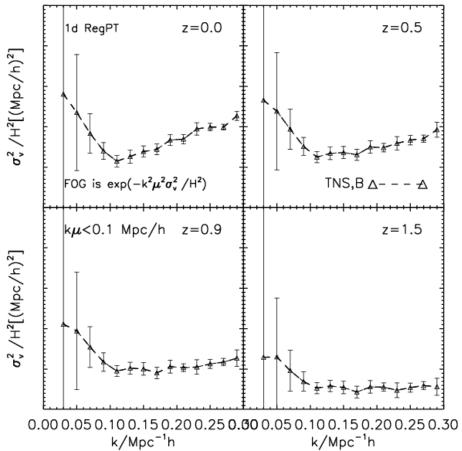
$$\left\langle \theta(\mathbf{k}_1) \Big\{ \delta(\mathbf{k}_2) + f \frac{k_{2z}^2}{k_2^2} \theta(\mathbf{k}_2) \Big\} \Big\{ \delta(\mathbf{k}_3) + f \frac{k_{3z}^2}{k_3^2} \theta(\mathbf{k}_3) \Big\} \right\rangle$$

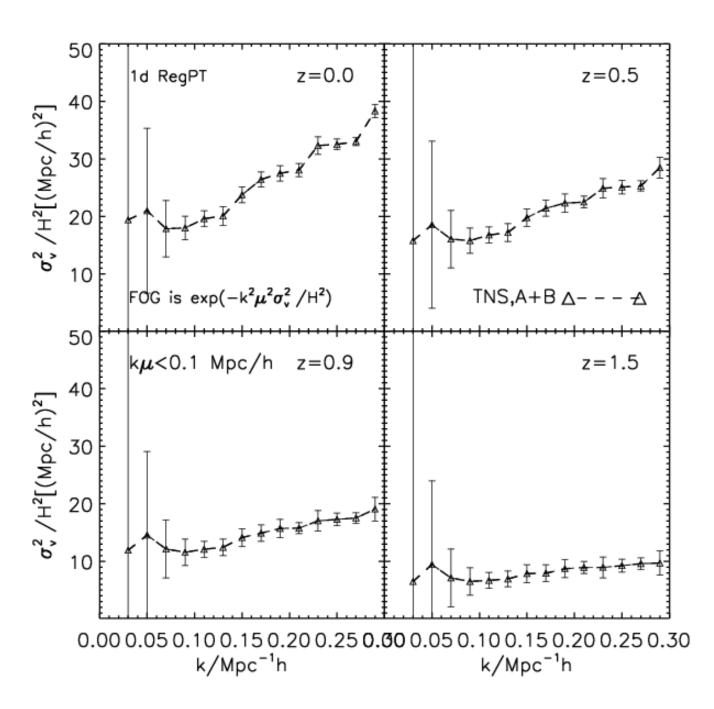
$$= (2\pi)^3 \delta_D(\mathbf{k}_1 + \mathbf{k}_2 + \mathbf{k}_3) B_{\sigma}(\mathbf{k}_1, \mathbf{k}_2, \mathbf{k}_3).$$

$$B(k, \mu) = (k\mu f)^2 \int \frac{d^3 \mathbf{p}}{(2\pi)^3} F(\mathbf{p}) F(\mathbf{k} - \mathbf{p});$$

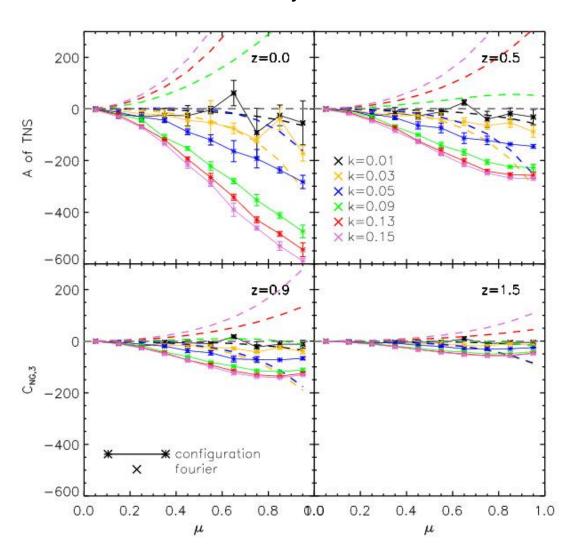
$$F(\mathbf{p}) = \frac{p_z}{p^2} \Big\{ P_{\delta\theta}(\mathbf{p}) + f \frac{p_z^2}{p^2} P_{\theta\theta}(\mathbf{p}) \Big\},$$

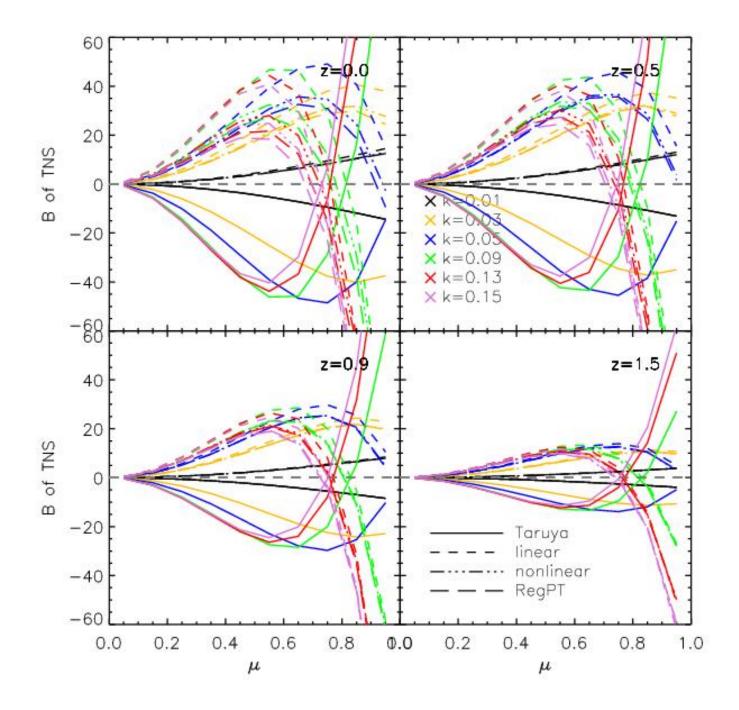


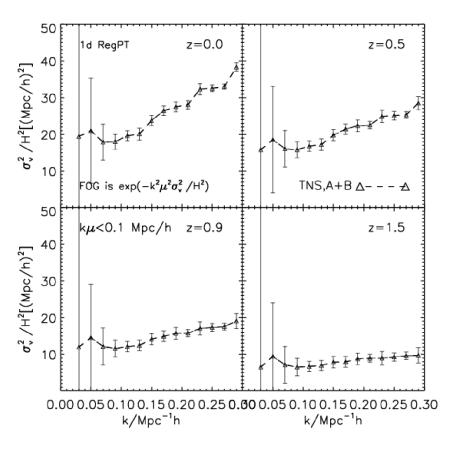




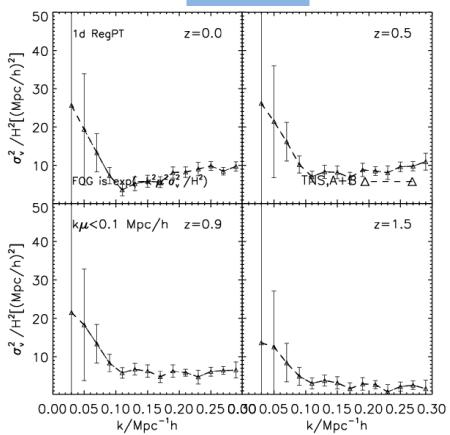
Test of A, B terms







simulation



Further improvment

- v. p.......
- (ii) For cumulants $\langle A_1^n \rangle_c = \langle [u_z(\mathbf{r}) u_z(\mathbf{r}')]^n \rangle_c$ of any integer value n, the spatial correlations between different positions are ignored, and the nonvanishing cumulants are assumed to be expressed as $\langle A_1^n \rangle_c \simeq 2\langle u_z^n \rangle_c = 2c_n\sigma_v^n$ for even n, with c_n being constants. Taruya et al. arXiv:1006.0699
- C term: velocity correlation $C(k, \mu) = (k\mu f)^2 \int \frac{d^3p d^3q}{(2\pi)^3} \delta_D(k-p-q) \frac{\mu_p^2}{p^2} P_{\theta\theta}(p)$

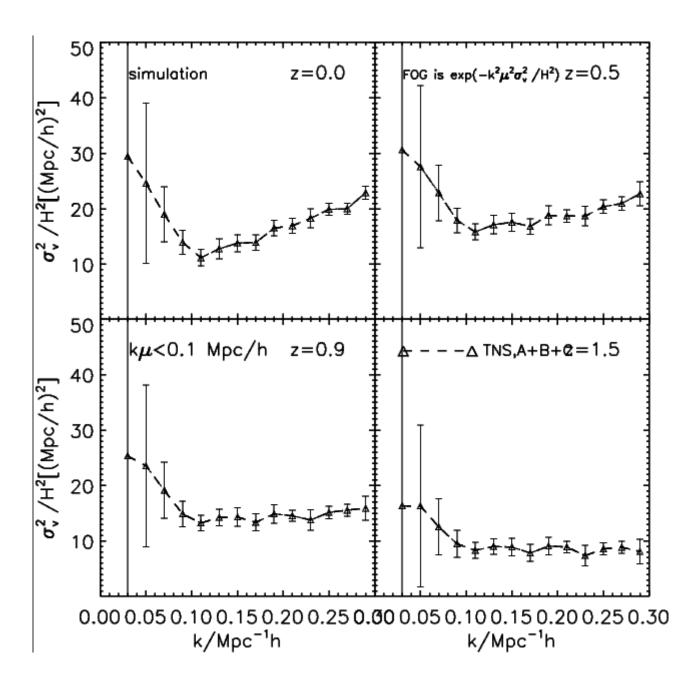
$$C(k, \mu) = (k\mu f)^{2} \int \frac{d^{3} p d^{3} q}{(2\pi)^{3}} \, \delta_{D}(k - p - q) \frac{\mu_{p}^{2}}{p^{2}} P_{\theta\theta}(p)$$

$$\times \{ P_{\delta\delta}(q) + 2f \mu_{q}^{2} P_{\delta\theta}(q) + f^{2} \mu_{q}^{4} P_{\theta\theta}(q) \}$$

$$\simeq (k\mu f)^{2} \int \frac{d^{3} p d^{3} q}{(2\pi)^{3}} \, \delta_{D}(k - p - q) \frac{\mu_{p}^{2}}{p^{2}}$$

$$\times (1 + f \mu_{q}^{2})^{2} P_{\text{lin}}(p) P_{\text{lin}}(q)$$
(24)

• Zhang13 model. (P. Zhang, J. Pan, and Y. Zheng, 1207.2722.)



Velocity bias or not?

A fundamental problem in peculiar velocity cosmolosy

In linear theory:

Desjacques & Sheth 0909.4544

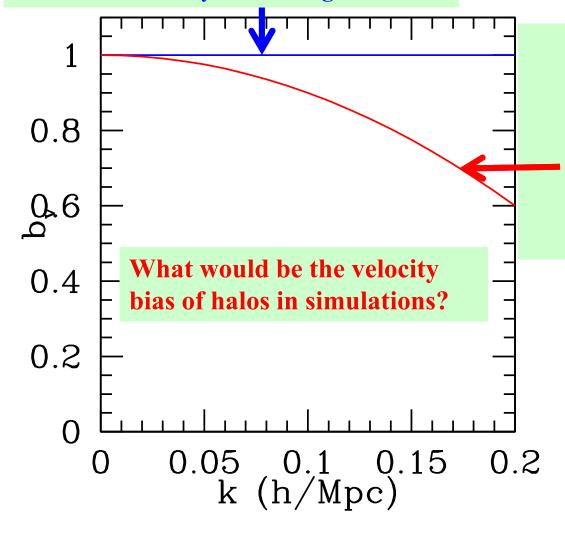
$$P_{\rm pk}^s(k,\mu) = \exp(-f^2 \sigma_{\rm vel}^2 k^2 \mu^2) \left[b_{\rm pk}(k) + b_{\rm vel}(k) f \mu^2 \right]^2 P_{\delta}(k)$$

Cosmological observations: galaxy velocity field (power spectrum)

$$b_v(k) \equiv \sqrt{\frac{P_g^v(k)}{P_{\rm DM}^v(k)}} = 1?$$

Cosmological observations: dark matter velocity field (power spectrum)

Peculiar velocity cosmology by default assumes no velocity bias at large scale:



Environmental effect:
halos/galaxies locate at special
regions around density peaks.
Proto-halos/linearly evolved
density peaks (BBKS 1986;
Desjacques & Sheth 2010)
have velocity bias

$$b_v \simeq 1 - \frac{\sigma_0^2}{\sigma_1^2} k^2$$

$$\frac{\sigma_v^2(\text{halos})}{\sigma_v^2(\text{DM})} = 1 - \frac{\sigma_0^2}{\sigma_{-1}\sigma_{+1}}$$

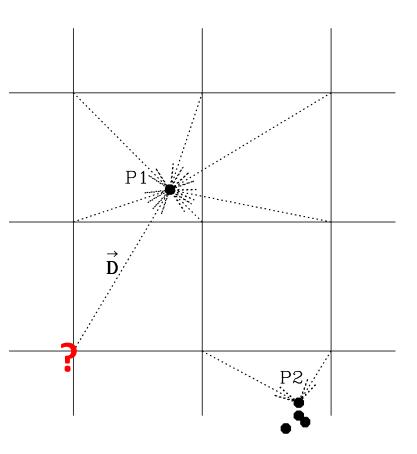
$$\sigma_n^2 \propto \int_0^\infty dk k^{2(n+1)} P_m(k,z) W^2(k,M)$$

Truth is:

the velocity bias disappear. First is the stochasticity in the proto-halo—halo relation. A fraction of halos today do not correspond to initial density peaks and a fraction of initial density peaks do not evolve into halos today (e.g., [15]). Second, halos move from their initial positions. They tend to move towards each other and, hence, modify their velocity correlation. Third, the density and velocity evolution has non-negligible nonlinearity (e.g., [15,22]) and, hence, non-Gaussianity. This alters the predicted velocity bias based on Gaussian statistics.

The sampling artifact

- Velocity field from most RSD models is volume weighted
- Where there is no particle, the velocity is usually non-zero. It can be large. The sampling on the volume weighted velocity field is biased/imperfect
- The sampling artifact: inevitable for inhomogeneously distributed objects. Severe for sparse populations. Persists for NP, Voronoi and Delaunay tessellation.
- The sampling and the signal are neither completely uncorrelated nor completely correlated. Hard to correct straightforwardly
- Can be fully described in the language of the D
 field (ZPJ, Zheng & Jing, 2014), similar to CMB
 lensing
 PJZ's PPT



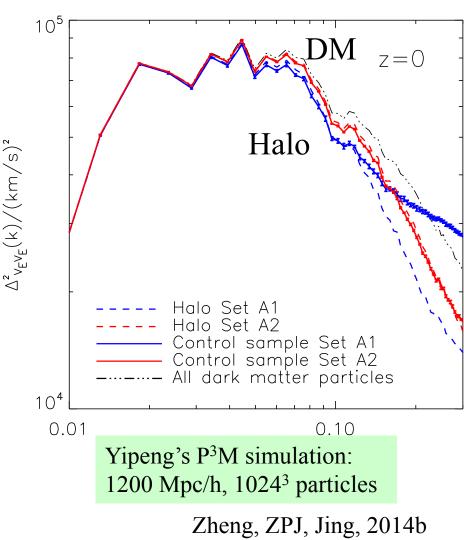
Severe sampling artifact



can be misinterpreted as a "velocity bias"

$$b_v \equiv \sqrt{\frac{P_{h,vv}}{P_{DM,vv}}}$$

- Naive comparison between the raw measurements of halo velocity and DM velocity gives a apparent b_v<1
- Illusion caused by the sampling artifact
- Unphysical numerical effect.
 But can be misinterpreted as
 a "velocity bias"



Understanding the sampling artifact

$$\hat{\mathbf{v}}(\mathbf{x}) = \mathbf{v}(\mathbf{x}_P(\mathbf{x}))$$
. $\mathbf{D}(\mathbf{x}) \equiv \mathbf{x}_P(\mathbf{x}) - \mathbf{x}$

Neglect v-D correlation.

$$\hat{P}_{ij}(\mathbf{k}) = \sum_{\mathbf{q}} P_{ij}(\mathbf{q}) W(\mathbf{q}, \mathbf{q}') . W(\mathbf{q}, \mathbf{q}') \equiv \frac{1}{N_{\text{grid}}^2} \sum_{\mathbf{x} \neq \mathbf{x}'} S(\mathbf{q}, \mathbf{r}) e^{i\mathbf{q}' \cdot \mathbf{r}} S(\mathbf{q}, \mathbf{r}) = \left\langle e^{i\mathbf{q} \cdot (\mathbf{D}' - \mathbf{D})} \right\rangle$$

Neglect correlation in D

Including the correlation in D.Not exact.

$$\hat{P}_{E}^{(1)}(k) \simeq P_{E}(k)S(k)$$

$$S(k) \equiv S(\mathbf{k}, \mathbf{r} \to \infty) = \left| \left\langle e^{i\mathbf{k}\cdot\mathbf{D}} \right\rangle \right|^{2} = e^{-\frac{1}{3}k^{2}\sigma_{D}^{2} + \cdots}$$

$$\hat{P}_{E}(k) \simeq P_{E}(k)S(k)e^{\frac{1}{3}k^{2}\xi_{D}(r_{\text{eff}}=\alpha/k)}$$

$$= P_{E}(k)\langle e^{i\mathbf{q}\cdot\mathbf{D}}\rangle^{2}e^{\frac{1}{3}k^{2}\xi_{D}(r_{\text{eff}}=\alpha/k)}$$

ZPJ, Zheng & Jing, 2014

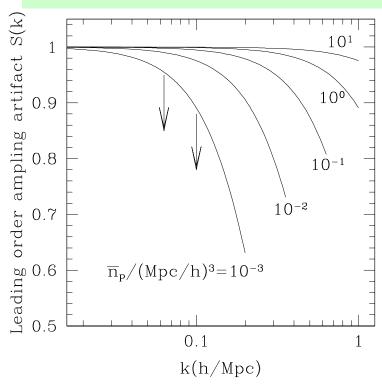
Zheng, ZPJ & Jing, 2014a

- Our model works.
- But improvements are needed
 - Take correlation in D fully into account
 - Take v-D correlation into account

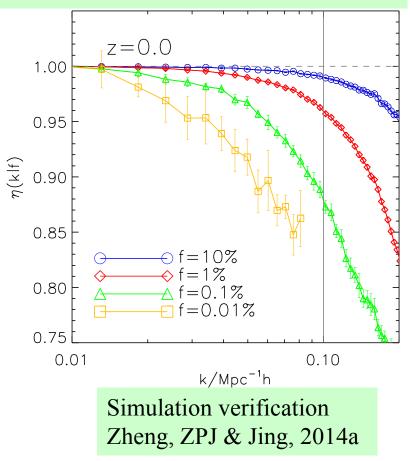
PJZ's PPT

Theory and simulation of the sampling artifact

The measured velocity power spectrum The real velocity power spectrum



Theory prediction: ZPJ, Zheng & Jing, 2014



ZPJ's PPT

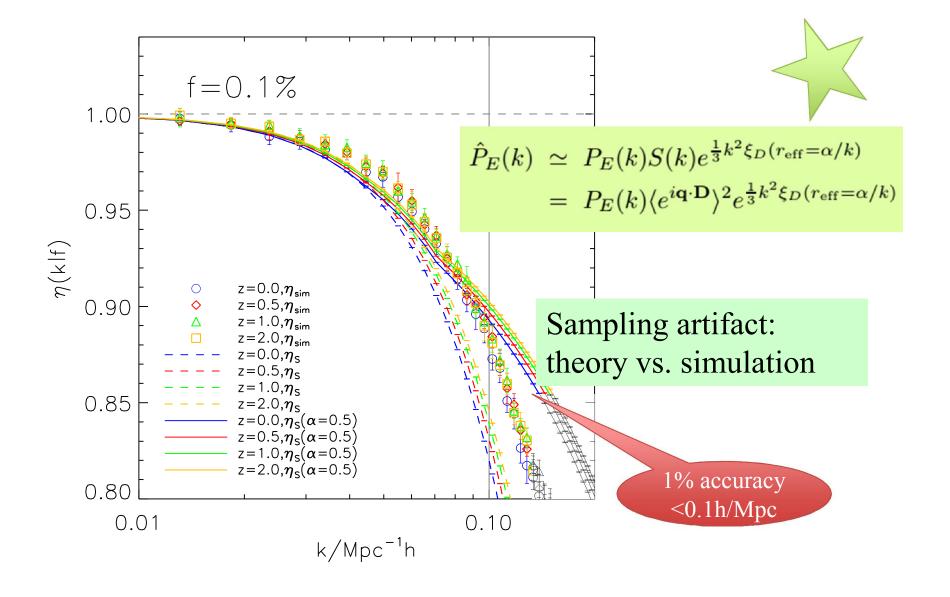
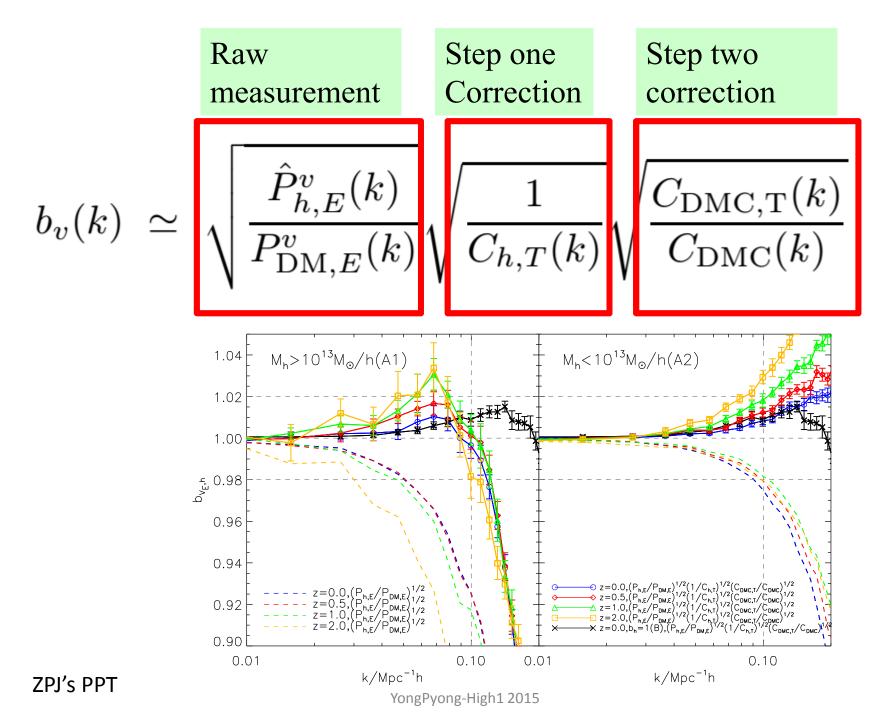
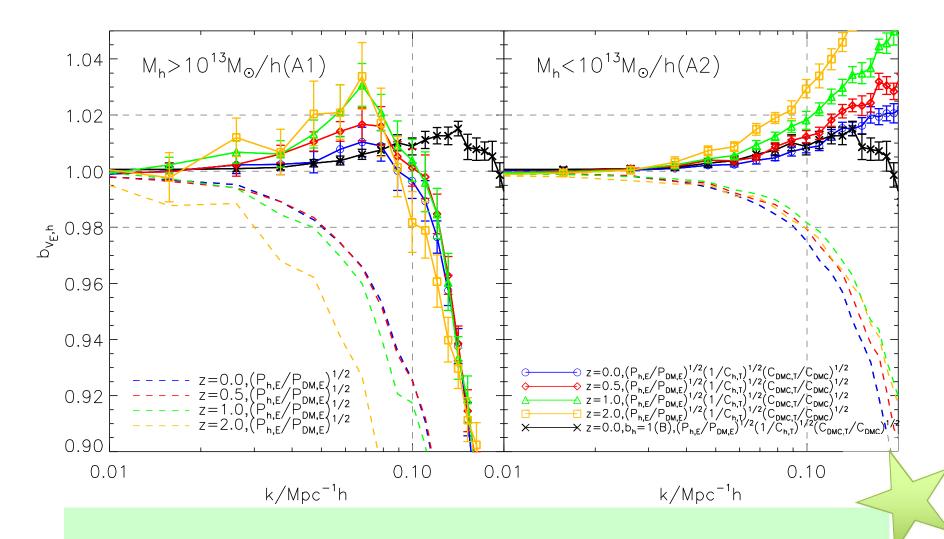


FIG. 4: Same as Fig. 3, but for f = 0.1% ($\bar{n}_P = 6.2 \times 10^{-4} (\text{Mpc/}h)^{-3}$). Eq. 15 (solid curves) improves over Eq. 7 (dashed curves) from $\sim 6\%$ at k = 0.1h/Mpc to 1%.





- 1. Velocity bias vanishes at k<0.1 h/Mpc. Consolidates peculiar velocity cosmology
- 2. Velocity bias at k>0.1h/Mpc? Poses a challenge

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For discussions

- Needs theory explanation
- Needs more accurate quantification
 - Need improved understanding of the sampling artifact
- Needs to extend to galaxies (mock catalog)
- Perhaps needs new velocity assignment (e.g. Jun Zhang's idea)
- Cosmological applications
 - Could be smoking guns of MG
 - Promising tests of the equivalence principle (ongoing work with Zheng Yi, Yipeng, Baojiu Li & De-Chang Dai)