

# On Some Models of Universal Expansion in General Relativity Using Otsuki Connections

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**Abstract.** An Otsuki connection  $\Gamma$  is a cross section of the bundle  $T(M) \otimes \mathcal{D}^2(M)$  and they can be understood as generalized objects of the affine connections. Briefly, the difference between these two theories is that an Otsuki connection  $\Gamma$  is an affine connection if and only if the principal part  $\lambda(\Gamma)$  of  $\Gamma$ , which is a homomorphism of the tangent bundle  $T(M)$ , is the identity map. We consider some special class  $\Gamma(\Psi, G)$  of  $\Gamma$ . Using  $\Gamma(\Psi, G)$ , this paper presents universal expansion-like models which are exact solutions of some partial differential equations.

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## §1. Basic Concepts and Preliminaries

A cross section  $\Gamma$  on the vector bundle  $T(M) \otimes \mathcal{D}^2(M)$  is called an Otsuki connection, where  $T(M)$  and  $\mathcal{D}^2(M)$  are the tangent bundle and the cotangent bundle of order 2 on a smooth manifold  $M$  respectively. Using local coordinates  $(u^\lambda)$ ,  $\Gamma$  is written as follows:

$$\Gamma = \frac{\partial}{\partial u^\lambda} \otimes \left( P_\mu^\lambda d^2 u^\mu + \Gamma_{\mu\nu}^\lambda du^\mu \otimes du^\nu \right).$$

It is easy to see that the  $P = (P_\mu^\lambda)$  transforms as a tensor field of type  $(1, 1)$  under coordinates changes. The tensor field  $P = (P_\mu^\lambda)$ , which is denoted by  $\lambda(\Gamma)$ , is called the principal part of  $\Gamma$ . According to Otsuki [6, 7], the covariant derivative  $\Gamma_X Y$  is defined by

$$\Gamma_X Y = (X(Y^\lambda)P_\lambda^\mu + \Gamma_{\lambda\nu}^\mu X^\lambda Y^\nu) \frac{\partial}{\partial u^\mu},$$

where  $X, Y$  and  $\Gamma_X Y$  are tangent vector fields on  $M$ . The operator  $\Gamma_X$  has the following properties:

1.  $\Gamma_{fX+gY}Z = f\Gamma_XZ + g\Gamma_YZ,$
2.  $\Gamma_X(Y + Z) = \Gamma_XY + \Gamma_XZ,$
3.  $\Gamma_XfY = X(f)P(Y) + f\Gamma_XY,$  where  $f, g$  are functions on  $M$ .

It is routine work to extend the covariant derivative to arbitrary tensor fields. For example, if  $F$  is a tensor field of type  $(0, 2)$ , then  $\Gamma_XF$  is defined by

$$\Gamma_XF(Y, Z) = X(F(PY, PZ)) - F(\Gamma_XY, PZ) - F(PY, \Gamma_XZ).$$

We put

$$T(X, Y) = \Gamma_XY - \Gamma_YX - P[X, Y].$$

This element becomes a tensor field of type  $(0, 2)$  and is called the torsion tensor field of  $\Gamma$ . Any geodesic  $\gamma$  in  $M$  with an Otsuki connection  $\Gamma$  is given by a solution of the system of the ordinary differential equation of order 2 on  $M$ :

$$P_\mu^\lambda \frac{d^2 u^\mu}{ds^2} + \Gamma_{\mu\nu}^\lambda \frac{du^\mu}{ds} \frac{du^\nu}{ds} = 0,$$

where  $s$  is an affine parameter of the connection.

Let  $P = (P_\mu^\lambda)$  and  $G = (g_{\lambda\mu})$  be a regular tensor field of type  $(1, 1)$  and a non-singular tensor field of type  $(0, 2)$  on  $M$ . We put

$$\tilde{G}(X, Y) = G(PX, PY).$$

Using the terminology of Otsuki connections, the Levi-Civita connection  $\tilde{\nabla}$  with respect to  $\tilde{G}$  is written by

$$\tilde{\nabla} = \frac{\partial}{\partial u^\lambda} \otimes \left( \delta_\mu^\lambda d^2 u^\mu + \left\{ \tilde{\lambda}_{\mu\nu} \right\} du^\mu \otimes du^\nu \right),$$

where  $\left\{ \tilde{\lambda}_{\mu\nu} \right\}$  are the Christoffel symbols of  $\tilde{G} = (\tilde{g}_{\lambda\mu})$ . We define an Otsuki connection

$$P\tilde{\nabla} = \frac{\partial}{\partial u^\lambda} \otimes \left( P_\mu^\lambda d^2 u^\mu + P_\delta^\lambda \left\{ \tilde{\delta}_{\mu\nu} \right\} du^\mu \otimes du^\nu \right).$$

It is easy to see the following fundamental properties of  $P\tilde{\nabla}$ .

- 1  $P = \lambda(\Gamma).$
- 2  $(P\tilde{\nabla})_X G = 0.$
- 3  $P\tilde{\nabla}$  is torsion free.
- 4  $\gamma$  is a geodesic of  $\tilde{\nabla}$  if and only if it is a geodesic of  $P\tilde{\nabla}.$

Conversely  $\Gamma = P\tilde{\nabla}$  is uniquely determined by the above  $\mathbf{1}\sim\mathbf{3}$ , which we write

$$\Gamma = P\tilde{\nabla} = \Gamma(P, G).$$

The Otsuki connection  $\Gamma$ , which we will consider in this paper, is a case  $P = \Psi I$  and denoted by  $\Gamma(\Psi, G)$ , where  $\Psi$  is a function on  $M$  and  $I$  is the fundamental unit tensor field of type  $(1, 1)$ .  $\Gamma(\Psi, G)$  seems to have a meaning only where  $\Psi$  does not vanish, but any function  $\Psi$  on  $M$  is available for  $\Gamma(\Psi, G)$  because it can be written locally as follows:

$$\begin{aligned}\Gamma(\Psi, G) &= \frac{\partial}{\partial u^\lambda} \otimes \left( \Psi d^2 u^\lambda + \Gamma_{\mu\nu}^\lambda du^\mu \otimes du^\nu \right), \\ \Gamma_{\mu\nu}^\lambda &= \Psi \{_{\mu\nu}^\lambda\} + \left( \frac{\partial \Psi}{\partial u^\mu} \delta_\nu^\lambda + \frac{\partial \Psi}{\partial u^\nu} \delta_\mu^\lambda + \frac{\partial \Psi}{\partial u^\sigma} g^{\sigma\lambda} g_{\mu\nu} \right),\end{aligned}$$

where we use the apparatuses on a Riemannian manifold  $(M, G)$ . Using an affine parameter  $s$  of  $\Gamma(\Psi, G)$ , equations of a geodesic become

$$(1) \quad \Psi \frac{d^2 u^\lambda}{ds^2} + \Gamma_{\mu\nu}^\lambda \frac{du^\mu}{ds} \frac{du^\nu}{ds} = 0.$$

We define a set  $Sing(\Gamma) \subset \mathbf{M}$  and a metric  $\tilde{G}$  by

$$Sing(\Gamma) = \{x \in \mathbf{M} \mid \Psi(x) = 0\}, \quad \tilde{G} = \Psi^2 G.$$

The next lemma is a special case of the above property 4, which says that a space  $M \setminus Sing(\Gamma)$  with an Otsuki connection  $\Gamma = \Gamma(\Psi, G)$  and a Riemannian manifold  $(M \setminus Sing(\Gamma), \tilde{G})$  are geodesically equivalent in the following sense.

**Lemma 1.** *A curve  $\gamma(s)$  in  $M \setminus Sing(\Gamma)$  is a geodesic in the sense of Otsuki geometry of  $\Gamma(\Psi, G)$  if and only if it is a geodesic in the sense of Riemannian geometry of  $(M \setminus Sing(\Gamma), \tilde{G})$ .*

Lemma 1 shows that  $\tilde{G} = \Psi^2 G$  has an important meaning in  $\Gamma(\Psi, G)$  geometry, which we call the essential metric of an Otsuki connection  $\Gamma(\Psi, G)$ .

In the paper [4] we define a function  $S_{\Gamma(\Psi, G)}$  and the condition (A) as follows:

$$(A) \quad \delta \int_{\mathbf{M}} S_{\Gamma(\Psi, G)} dV_G = 0.$$

Using local coordinates  $(u^\lambda)$  and the apparatuses on the Riemannian manifold  $(M, G)$ , the condition (A) becomes as follows:

$$\begin{aligned}\Psi(R^{\mu\nu} &- \frac{1}{2}g^{\mu\nu}S) - \frac{1}{2}\nabla_\lambda \nabla_\kappa (\Psi^3)(g^{\mu\lambda}g^{\nu\kappa} - g^{\mu\nu}g^{\lambda\kappa}) \\ &+ 12(\nabla_\lambda \Psi)(\nabla_\kappa \Psi)(g^{\mu\lambda}g^{\nu\kappa} - \frac{1}{2}g^{\mu\nu}g^{\lambda\kappa})\Psi = 0, \\ \Psi(\Delta &- \frac{1}{8}S) + \frac{1}{2}g^{\mu\nu}(\nabla_\mu \Psi)(\nabla_\nu \Psi) = 0,\end{aligned}$$

where  $S$ ,  $\Delta$  are the scalar curvature, the Laplace-Beltrami operator of  $(M, G)$ . It appears very difficult to find non-trivial solutions, which means solutions with  $\Psi$  not being constant, of the above equations. However, using a function  $h$  and a metric  $\overline{G}$ , which are defined by

$$h = \frac{\sqrt{3}}{2} \log \Psi, \quad \overline{G} = \Psi^3 G,$$

the equations become the following simpler forms [5]:

$$\begin{aligned} \overline{R}^{\mu\nu} - \frac{1}{2} \overline{g}^{\mu\nu} \overline{S} + (\overline{g}^{\mu\nu} \overline{g}^{\alpha\beta} - \overline{g}^{\mu\alpha} \overline{g}^{\nu\beta}) (\overline{\nabla}_\alpha h) (\overline{\nabla}_\beta h) &= 0, \\ \overline{\Delta}(h) &= 0, \end{aligned}$$

where we use the apparatuses on Riemannian manifold  $(M, \overline{G})$ . Rewriting these equations to the covariant forms, we have

$$(2) \quad R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} S = (2\delta_\mu^\alpha \delta_\nu^\beta - g_{\mu\nu} g^{\alpha\beta}) (\nabla_\alpha h) (\nabla_\beta h),$$

$$(3) \quad \Delta(h) = 0,$$

where we use the apparatuses on  $(M \setminus \text{Sing}(\Gamma), \overline{G})$  but abbreviate the bar for convenience, which we do not think causes any confusion and we will use these notation from now on. (2) and (3) are the Euler-Lagrange equations of a Lagrange density  $L(h, \overline{G})$  which is defined as follows [5]:

$$L(h, \overline{G}) = g^{\mu\nu} \left[ \{\overset{\alpha}{\underset{\mu}{\beta}}\} \{\overset{\beta}{\underset{\nu}{\alpha}}\} - \{\overset{\alpha}{\underset{\mu\nu}}\} \{\overset{\beta}{\underset{\alpha\beta}}\} + 2(\nabla_\mu h)(\nabla_\nu h) \right] \sqrt{-|\overline{G}|},$$

where  $(M \setminus \text{Sing}(\Gamma), \overline{G})$  is a 4-dimensional Lorentz manifold and  $|\overline{G}| = \det(g_{\lambda\mu})$ . In the same paper [5] we look for solutions  $\Gamma(\Psi, G)$  of the above equations under the condition that  $\Gamma(\Psi, G)$  has the spherical symmetry and find two interesting families of Otsuki connections, one of which is the schwartzshild space-time and the other is peculiar to the theory of Otsuki connections  $\Gamma(\Psi, G)$ .

In Section 2 we will find exact solutions  $\Gamma(\Psi, G)$  of the equations, whose essential metric has the following form:

$$\overline{G} = -dw^2 + R^2(w)D(r)(dx^2 + dy^2 + dz^2).$$

Taking the results in advance,  $D(r)$  becomes:

$$D(r) = \left( 1 + \frac{\varepsilon r^2}{4} \right)^{-2},$$

where  $\varepsilon = -1, 0, 1$ . Some elementary properties of the functions  $R(w)$  will be discussed in Section 3.

The following ranges of indices are used throughout this paper:

$$1 \leq i, j, k, \dots \leq 3, \quad 0 \leq \alpha, \beta, \gamma, \dots \leq 3.$$

## §2. Universal Expansion Models by $\Gamma(\Psi, G)$

We consider a metric  $\overline{G}$  and a function  $h$  of the following forms:

$$\begin{aligned}\overline{G} &= g_{\lambda\mu} dx^\lambda dx^\mu \\ &= -B(t, r) dt^2 + A(t, r)(dx^2 + dy^2 + dz^2), \\ h &= h(t),\end{aligned}$$

where  $r^2 = x^2 + y^2 + z^2$  and we often use  $t, x, y, z$  instead of  $x^0, x^1, x^2, x^3$ . Using these forms, the Christoffel symbols  $\{\lambda_{\mu\nu}\} = \{\lambda_{\nu\mu}\}$  of  $\overline{G}$  become as follows:

$$\begin{aligned}\{^t_{tt}\} &= \{^0_{00}\} = \frac{1}{2} \frac{B_t}{B}, \{^0_{0i}\} = \{^i_{i0}\} = \frac{1}{2} \frac{B_r}{B} \frac{x^i}{r}, \\ \{^0_{ij}\} &= \{^i_{ji}\} = \frac{1}{2} \frac{A_t}{B} \delta_{ij}, \{^i_{00}\} = \frac{1}{2} \frac{B_r}{A} \frac{x^i}{r}, \\ \{^i_{0j}\} &= \{^j_{j0}\} = \frac{1}{2} \frac{A_t}{A} \delta_{ij}, \\ \{^i_{jk}\} &= \{^k_{kj}\} = \frac{1}{2} \frac{A_r}{A} \left( \frac{x^k}{r} \delta_{ij} + \frac{x^j}{r} \delta_{ik} - \frac{x^i}{r} \delta_{jk} \right),\end{aligned}$$

where  $A_t = \frac{\partial A}{\partial t}$ ,  $A_r = \frac{\partial A}{\partial r}$ , etc.. Components of Ricci tensor and the scalar curvature  $S$  of  $\overline{G}$  are given as follows:

$$\begin{aligned}R_{00}(\equiv R_{tt}) &= -\frac{3}{2} \left( \frac{A_t}{A} \right)_t - \frac{3}{4} \left( \frac{A_t}{A} \right)^2 + \frac{3}{4} \left( \frac{A_t}{A} \right) \left( \frac{B_t}{B} \right) \\ &\quad + \frac{1}{2} \frac{B}{A} \left\{ \left( \frac{B_1}{B} \right)_1 + \left( \frac{B_2}{B} \right)_2 + \left( \frac{B_3}{B} \right)_3 \right\} \\ &\quad + \frac{1}{4} \frac{B}{A} \left\{ \left( \frac{A_1}{A} \right) \left( \frac{B_1}{B} \right) + \left( \frac{A_2}{A} \right) \left( \frac{B_2}{B} \right) + \left( \frac{A_3}{A} \right) \left( \frac{B_3}{B} \right) \right\} \\ &\quad + \frac{1}{4} \frac{B}{A} \left\{ \left( \frac{B_1}{B} \right)^2 + \left( \frac{B_2}{B} \right)^2 + \left( \frac{B_3}{B} \right)^2 \right\}, \\ R_{0k}(\equiv R_{k0}) &= \left( \frac{A_t}{A} \right)_k + \frac{1}{2} \left( \frac{A_t}{A} \right) \left( \frac{B_k}{B} \right), \\ R_{kk} &= \frac{1}{2} \frac{A}{B} \left( \frac{A_t}{A} \right)_t + \frac{3}{4} \frac{A}{B} \left( \frac{A_t}{A} \right)^2 - \frac{3}{4} \frac{A}{B} \left( \frac{A_t}{A} \right) \left( \frac{B_t}{B} \right) \\ &\quad - \frac{1}{2} \left\{ \left( \frac{A_1}{A} \right)_1 + \left( \frac{A_2}{A} \right)_2 + \left( \frac{A_3}{A} \right)_3 \right\} \\ &\quad - \frac{1}{4} \left\{ \left( \frac{A_1}{A} \right)^2 + \left( \frac{A_2}{A} \right)^2 + \left( \frac{A_3}{A} \right)^2 \right\} \\ &\quad - \frac{1}{2} \left\{ \left( \frac{A_k}{A} \right)_k + \left( \frac{B_k}{B} \right)_k \right\} + \frac{1}{4} \left( \frac{A_k}{A} \right)^2 - \frac{1}{4} \left( \frac{B_k}{B} \right)^2,\end{aligned}$$

$$\begin{aligned}
R_{km} (= R_{mk}) &= -\frac{1}{2} \left( \frac{A_m}{A} \right)_k - \frac{1}{2} \left( \frac{B_m}{B} \right)_k + \frac{1}{4} \left( \frac{A_k}{A} \right) \left( \frac{A_m}{A} \right) \\
&\quad + \frac{1}{4} \left( \frac{A_k}{A} \right) \left( \frac{B_m}{B} \right) + \frac{1}{4} \left( \frac{A_m}{A} \right) \left( \frac{B_k}{B} \right) - \frac{1}{4} \left( \frac{B_k}{B} \right) \left( \frac{B_m}{B} \right),
\end{aligned}$$

where  $k \neq m$ ,

$$\begin{aligned}
S &= \frac{3}{B} \left( \frac{A_t}{A} \right)_t + \frac{3}{B} \left( \frac{A_t}{A} \right)_t^2 - \frac{3}{2} \frac{1}{B} \left( \frac{A_t}{A} \right) \left( \frac{B_t}{B} \right) \\
&\quad - \frac{2}{A} \left\{ \left( \frac{A_1}{A} \right)_1 + \left( \frac{A_2}{A} \right)_2 + \left( \frac{A_3}{A} \right)_3 \right\} \\
&\quad - \frac{1}{A} \left\{ \left( \frac{B_1}{B} \right)_1 + \left( \frac{B_2}{B} \right)_2 + \left( \frac{B_3}{B} \right)_3 \right\} \\
&\quad - \frac{1}{2} \frac{1}{A} \left\{ \left( \frac{A_1}{A} \right)^2 + \left( \frac{A_2}{A} \right)^2 + \left( \frac{A_3}{A} \right)^2 \right\} \\
&\quad - \frac{1}{4} \left\{ \left( \frac{A_1}{A} \right) \left( \frac{B_1}{B} \right) + \left( \frac{A_2}{A} \right) \left( \frac{B_2}{B} \right) + \left( \frac{A_3}{A} \right) \left( \frac{B_3}{B} \right) \right\} \\
&\quad - \frac{1}{2} \frac{1}{A} \left\{ \left( \frac{B_1}{B} \right)^2 + \left( \frac{B_2}{B} \right)^2 + \left( \frac{B_3}{B} \right)^2 \right\},
\end{aligned}$$

where we use the following formulas and notations:

$$\begin{aligned}
R_{\mu\nu} &= R_{\nu\mu} = \frac{\partial}{\partial x^\lambda} \{\lambda_{\mu\nu}\} - \frac{\partial}{\partial x^\nu} \{\lambda_{\mu\lambda}\} + \{\lambda_{\kappa\lambda}\} \{\kappa_{\mu\nu}\} - \{\lambda_{\kappa\nu}\} \{\kappa_{\mu\lambda}\}, \\
S &= g^{\mu\nu} R_{\mu\nu}, \\
A_1 &= \frac{\partial A}{\partial x^1}, \quad A_2 = \frac{\partial A}{\partial x^2}, \quad A_3 = \frac{\partial A}{\partial x^3} \quad \text{etc.}
\end{aligned}$$

Using these equalities, the left side of (2), which are denoted by  $G_{\mu\nu}$  become as follows:

$$\begin{aligned}
G_{tt} &= R_{tt} - \frac{1}{2} g_{tt} S = R_{tt} + \frac{1}{2} B S \\
&= \frac{3}{4} \left( \frac{A_t}{A} \right)_t^2 - \frac{A}{B} \left\{ \left( \frac{A_1}{A} \right)_1 + \left( \frac{A_2}{A} \right)_2 + \left( \frac{A_3}{A} \right)_3 \right\} \\
&\quad - \frac{1}{4} \frac{B}{A} \left\{ \left( \frac{A_1}{A} \right)^2 + \left( \frac{A_2}{A} \right)^2 + \left( \frac{A_3}{A} \right)^2 \right\} \\
&\quad + \frac{1}{8} \frac{B}{A} \left\{ \left( \frac{A_1}{A} \right) \left( \frac{B_1}{B} \right) + \left( \frac{A_2}{A} \right) \left( \frac{B_2}{B} \right) + \left( \frac{A_3}{A} \right) \left( \frac{B_3}{B} \right) \right\}, \\
G_{kk} &= R_{kk} - \frac{1}{2} g_{kk} S = R_{kk} - \frac{1}{2} A S \\
&= -\frac{A}{B} \left( \frac{A_t}{A} \right)_t - \frac{3}{4} \frac{A}{B} \left( \frac{A_t}{A} \right)_t^2 + \frac{1}{2} \frac{A}{B} \left( \frac{A_t}{A} \right) \left( \frac{B_t}{B} \right)
\end{aligned}$$

$$\begin{aligned}
 & + \frac{1}{2} \left\{ \left( \frac{A_1}{A} \right)_1 + \left( \frac{A_2}{A} \right)_2 + \left( \frac{A_3}{A} \right)_3 \right\} \\
 & + \frac{1}{2} \left\{ \left( \frac{B_1}{B} \right)_1 + \left( \frac{B_2}{B} \right)_2 + \left( \frac{B_3}{B} \right)_3 \right\} \\
 & + \frac{1}{8} \left\{ \left( \frac{A_1}{A} \right) \left( \frac{B_1}{B} \right) + \left( \frac{A_2}{A} \right) \left( \frac{B_2}{B} \right) + \left( \frac{A_3}{A} \right) \left( \frac{B_3}{B} \right) \right\}, \\
 & + \frac{1}{4} \left\{ \left( \frac{B_1}{B} \right)^2 + \left( \frac{B_2}{B} \right)^2 + \left( \frac{B_3}{B} \right)^2 \right\} \\
 & - \frac{1}{2} \left( \frac{A_k}{A} \right)_k - \frac{1}{2} \left( \frac{B_k}{B} \right)_k + \frac{1}{4} \left( \frac{A_k}{A} \right)^2 - \frac{1}{4} \left( \frac{B_k}{B} \right)^2, \\
 G_{km} &= R_{km} - \frac{1}{2} g_{km} S = R_{km} \\
 &= -\frac{1}{2} \left( \frac{A_m}{A} \right)_k - \frac{1}{2} \left( \frac{B_m}{B} \right)_k + \frac{1}{4} \left( \frac{A_k}{A} \right) \left( \frac{A_m}{A} \right) \\
 &+ \frac{1}{4} \left( \frac{A_k}{A} \right) \left( \frac{B_m}{B} \right) + \frac{1}{4} \left( \frac{A_m}{A} \right) \left( \frac{B_k}{B} \right) - \frac{1}{4} \left( \frac{B_k}{B} \right) \left( \frac{B_m}{B} \right),
 \end{aligned}$$

where  $k \neq m$ . On the other hand, the right sides of (2), which are denoted by  $H_{\mu\nu}$ , become as follows:

$$\begin{aligned}
 H_{tt} &= (2\delta_t^\alpha \delta_t^\beta - g_{tt} g^{\alpha\beta}) \nabla_\alpha(h) \nabla_\beta(h) = (h_t)^2, \\
 H_{kk} &= (2\delta_k^\alpha \delta_k^\beta - g_{kk} g^{\alpha\beta}) \nabla_\alpha(h) \nabla_\beta(h) = \frac{A}{B} (h_t)^2, \\
 \text{the others} &= 0,
 \end{aligned}$$

where  $h_t = \frac{\partial h}{\partial t}$ . (2) becomes as follows:

$$\begin{aligned}
 (4) \quad G_{00} &= (h_t)^2, \\
 (5) \quad G_{kk} &= \frac{A}{B} (h_t)^2, \\
 (6) \quad G_{0k} &= G_{k0} = 0, \\
 (7) \quad G_{km} &= G_{mk} = 0,
 \end{aligned}$$

where  $k \neq m$ . Now we assume that  $A(t, r)$  has a form of  $A(t, r) = C(t)D(r)$ , then (6) becomes  $B_r C_t = 0$ . We assume  $B_r = 0$  i.e.  $B = B(t)$  and rewrite  $\overline{G}$  and  $h$  using the following new variable  $\tilde{t}$  such that  $\tilde{t} = \int^t \sqrt{B(s)} ds$  for  $t$ . Now  $\overline{G}$  and  $h$  become as follows:

$$\begin{aligned}
 \overline{G} &= -d\tilde{t}^2 + \tilde{A}(\tilde{t}, r)(dx^2 + dy^2 + dz^2), \\
 h(t) &= \tilde{h}(\tilde{t}),
 \end{aligned}$$

where  $\tilde{A}(\tilde{t}, r) = C(t)D(r) = \tilde{C}(\tilde{t})D(r)$ . Without loss of generality, we can assume as follows:

$$\overline{G} = -dt^2 + A(t, r)(dx^2 + dy^2 + dz^2),$$

$$h = h(t),$$

where  $A(t, r) = C(t)D(r)$ . Using these forms of  $\overline{G}$  and  $h$ , (4), (5) and (7) become as follows:

$$(8) \quad \frac{3}{4} \left( \frac{C_t}{C} \right)^2 + \frac{1}{CD^2} \left\{ D_{rr} + \frac{2}{r} D_r - \frac{3}{4D} (D_r)^2 \right\} = (h_t)^2,$$

$$(9) \quad - \left\{ C_{tt} - \frac{1}{4C} (C_t)^2 \right\} + \frac{1}{2D} \left\{ D_{rr} + \frac{1}{r} D_r - \frac{1}{D} (D_r)^2 \right\} = CD(h_t)^2,$$

$$(10) \quad - \frac{1}{2D} \left\{ D_{rr} - \frac{1}{r} D_r - \frac{3}{2D} (D_r)^2 \right\} = 0.$$

Equality (6) becomes as follows:

$$(11) \quad h_{tt} + \frac{3}{2C} (C_t h_t) = \frac{1}{2h_t C^3} \left\{ (h_t)^2 C^3 \right\}_t = 0.$$

(8)~(11) are the fundamental equations of this paper.

Using a new function:  $\frac{1}{D} = f^2$ , (10) becomes as follows:

$$-\frac{2}{f^3} \left( f_{rr} - \frac{1}{r} f_r \right) = 0,$$

where  $f_r = \frac{\partial f}{\partial r}$ ,  $f_{rr} = \frac{\partial^2 f}{\partial r^2}$ . Integrating this equality, we have

$$f(r) = 1 + \frac{\varepsilon r^2}{4}, \quad \varepsilon = -1, 0, 1,$$

and  $D(r)$  becomes as follows:

$$D(r) = \left( 1 + \frac{\varepsilon r^2}{4} \right)^{-2}, \quad \varepsilon = -1, 0, 1,$$

where we use a boundary condition such that

$$\lim_{r \rightarrow +\infty} D(r) = 1.$$

Putting these  $D(r)$  into (8), (9) and (11), we have the following:

$$(12) \quad \frac{3}{4} \left( \frac{C_t}{C} \right)^2 + \frac{3\varepsilon}{C} = (h_t)^2,$$

$$(13) \quad \frac{C_{tt}}{C} - \frac{1}{4} \left( \frac{C_t}{C} \right)^2 + \frac{\varepsilon}{C} = -(h_t)^2,$$

$$(14) \quad \left\{ (h_t)^2 C^3 \right\}_t = 0.$$



Differentiating (12) by  $t$ , we have

$$\frac{3}{2} \left( \frac{C_t}{C} \right) \left( \frac{C_{tt}}{C} \right) - \frac{3}{2} \left( \frac{C_t}{C} \right)^3 - \frac{3\varepsilon}{C} \left( \frac{C_t}{C} \right) = 2(h_t)(h_{tt}).$$

Using (14) to the right side of the above equality, we have as follows:

$$\begin{aligned} & -\frac{3}{2} \left( \frac{C_t}{C} \right) \left\{ \frac{3}{4} \left( \frac{C_t}{C} \right)^2 + \frac{3\varepsilon}{C} - (h_t)^2 \right\} \\ & + \frac{3}{2} \left( \frac{C_t}{C} \right) \left\{ \frac{C_{tt}}{C} - \frac{1}{4} \left( \frac{C_t}{C} \right)^2 + \frac{\varepsilon}{C} + (h_t)^2 \right\} = 0. \end{aligned}$$

This equality shows that (12) and (14) imply (13). Integrating (14), we have

$$(h_t)^2 = \frac{3\eta^2}{C^3}, \quad \eta \geq 0.$$

Substituting this equality into (12), we have

$$\frac{1}{4} \left( \frac{C_t}{C} \right)^2 + \frac{\varepsilon}{C} - \frac{\eta^2}{C^3} = 0.$$

Summerizing the preceding results of this section, we have

**Lemma 2.** *Let  $\Gamma(\Psi, G)$  be an Otsuki connection with the condition (A) and  $\overline{G}$  and  $h$  have forms such that*

$$\begin{aligned} \overline{G} &= -B(t, r)dt^2 + A(t, r)(dx^2 + dy^2 + dz^2), \\ h &= h(t), \end{aligned}$$

where  $B_t \neq 0$  and  $A(t, r) = C(t)D(r)$ . Then  $\overline{G}$  becomes

$$\overline{G} = -dt^2 + C(t)D(r)(dx^2 + dy^2 + dz^2)$$

and  $h(t)$ ,  $C(t)$  and  $D(r)$  satisfy the following equalities:

$$(15) \quad (h_t)^2 = \frac{3\eta^2}{C^3}, \quad \eta \geq 0,$$

$$(16) \quad D(r) = \left( 1 + \frac{\varepsilon r^2}{4} \right)^{-2}, \quad \varepsilon = -1, 0, 1,$$

$$(17) \quad \frac{1}{4} \left( \frac{C_t}{C} \right)^2 + \frac{\varepsilon}{C} - \frac{\eta^2}{C^3} = 0.$$

A case  $\eta = 0$  in Lemma 2 is easy to treat. Then, (15) implies  $h \equiv 0$ , which means that  $\Gamma(\Psi, G)$  is the Levi-Civita connection of Riemannian manifold  $(M, G)$ , where  $M \subseteq \mathbf{R}^4$ . (17) implies that  $C(t) = t^2$  for  $\varepsilon = -1$ ,  $C(t) \equiv 1$  for  $\varepsilon = 0$  and no solution for  $\varepsilon = 1$ . Now we have

**Lemma 3.** *For a case  $\eta = 0$  in Lemma 2,  $\Gamma(\Psi, G)$  becomes the Levi-Civita connection of Riemannian manifold  $(M, G)$ ,  $M \subseteq \mathbf{R}^4$ , such that  $G$  is either of the following two:*

$$\begin{aligned} G &= -dt^2 + t^2 \left(1 - \frac{r^2}{4}\right)^{-2} (dx^2 + dy^2 + dz^2), \\ G &= -dt^2 + dx^2 + dy^2 + dz^2. \end{aligned}$$

From now on we suppose  $\eta > 0$  and we define a function  $\zeta(t)$  by

$$C(t) = \eta^2 \zeta^2(t).$$

It is tedious to display every detail of calculations for all the cases  $\varepsilon = -1, 0, 1$ , but we give details of calculations for one case  $\varepsilon = -1$  and only the results for other two. Using  $\zeta(t)$ , (17) is written as follows:

$$(\zeta_t)^2 = \frac{1}{\eta^2} \left( \frac{1 + \zeta^4}{\zeta^4} \right).$$

Defining a non-negative function  $\vartheta(t)$  by

$$\zeta^2(t) = \sinh(\vartheta(t))$$

and inserting it into the above equality, we have

$$\cosh^2(\vartheta)(\vartheta_t)^2 = \frac{4}{\eta^2} \left( \frac{1 + \zeta^4}{\zeta^2} \right).$$

This equality is rewritten as follows:

$$(18) \quad dt = \frac{1}{2} \eta \sqrt{\sinh(\vartheta)} d\vartheta.$$

(18) shows that  $\vartheta(t)$  is the inverse function of

$$t(\vartheta) = \frac{1}{2} \int_0^\vartheta \sqrt{\sinh(s)} ds.$$

Using

$$C(t) = \eta^2 \zeta^2(t) = \eta^2 \sinh(\vartheta(t))$$

and (18) in (15), we have

$$(h_t)^2 = \frac{3}{\eta^2 \sinh^3(\vartheta)},$$

$$h_\vartheta = h_t \frac{dt}{d\vartheta} = \pm \frac{\sqrt{3}}{2} \left( \frac{1}{\sinh(\vartheta)} \right),$$

where  $h_\vartheta = \frac{\partial h}{\partial \vartheta}$ . Integrating the second equality of the aboves, we have

$$h(t) = \mp \frac{\sqrt{3}}{2} \int_{\vartheta(t)}^{\infty} \frac{ds}{\sinh(s)}.$$

Now we find  $\overline{G}$  and  $h$ , i.e. Otsuki connections  $\Gamma(\Psi, G)$ , as follows:

$$\begin{aligned} \overline{G} &= -dt^2 + \eta^2 \sinh(\vartheta(t)) \left( 1 - \frac{r^2}{4} \right)^{-2} (dx^2 + dy^2 + dz^2), \\ h(t) &= \pm \frac{\sqrt{3}}{2} \int_{\vartheta(t)}^{\infty} \frac{ds}{\sinh(s)}. \end{aligned}$$

The other cases are similar to the above calculations.

**Theorem 1.** *Under the same conditions as Lemma 2,  $\overline{G}$  and  $h(t)$  are given as follows:*

**(Riemannian Type)**

1.  $\varepsilon = 0$

$$\overline{G} = -dt^2 + dx^2 + dy^2 + dz^2.$$

2.  $\varepsilon = -1$

$$\overline{G} = -dt^2 + t^2 \left( 1 - \frac{r^2}{4} \right)^{-2} (dx^2 + dy^2 + dz^2).$$

**(Otsuki Type)**

1.  $\varepsilon = -1$

$$\begin{aligned} \overline{G} &= -dt^2 + \eta^2 \sinh(\vartheta(t)) \left( 1 - \frac{r^2}{4} \right)^{-2} (dx^2 + dy^2 + dz^2), \\ h(t) &= \pm \frac{\sqrt{3}}{2} \int_{\vartheta(t)}^{\infty} \frac{ds}{\sinh(s)}. \end{aligned}$$

2.  $\varepsilon = 0$  ( $t > 0$ )

$$\begin{aligned}\overline{G} &= -dt^2 + \mu^2 t^{\frac{2}{3}} \left(1 - \frac{r^2}{4}\right)^{-2} (dx^2 + dy^2 + dz^2), \quad \mu^3 = 3\eta^2, \\ h(t) &= \pm \frac{1}{\sqrt{3}} \log(t).\end{aligned}$$

3.  $\varepsilon = 1$  ( $0 \leq \vartheta \leq \pi$ )

$$\begin{aligned}\overline{G} &= -dt^2 + \eta^2 \sin(\vartheta(t)) \left(1 + \frac{r^2}{4}\right)^{-2} (dx^2 + dy^2 + dz^2), \\ h(t) &= \pm \frac{\sqrt{3}}{2} \int_{\vartheta(t)}^{\frac{\pi}{2}} \frac{ds}{\sin(s)},\end{aligned}$$

where  $\vartheta(t)$  is the inverse function of

$$t(\vartheta) = \frac{1}{2} \int_0^{\vartheta} \sqrt{\sinh(s)} ds.$$

### §3. The Essential Metrics, the Variable $w$ and the Function $R(w)$

As discussed in Section 1, neither a metric  $G$  nor  $\overline{G}$  but  $\tilde{G} \equiv \Psi^2 G = \Psi^{-1} \overline{G}$ , which is called the essential metric of  $\Gamma(\Psi, G)$ , has an important meaning on a manifold  $M$  with an Otsuki connection  $\Gamma(\Psi, G)$ . Lemma 1 says that any geodesic in  $M \setminus \text{Sing}(\Gamma)$  with Otsuki connection  $\Gamma(\Psi, G)$  is a geodesic in a Riemannian manifold  $(M \setminus \text{Sing}(\Gamma), \tilde{G})$  and vice versa, where  $\text{Sing}(\Gamma) \subseteq \mathbf{M}$  is defined as follows:

$$\text{Sing}(\Gamma) = \{x \in \mathbf{M} \mid \Psi(x) = 0\}.$$

Using a new variable  $w$ , which is defined by

$$w(t) = \int_0^t \Psi^{-\frac{1}{2}}(s) ds,$$

the essential metric  $\tilde{G}$  i.e.

$$\tilde{G} \equiv \Psi^{-1} G = -\Psi^{-1}(t) dt^2 + \Psi^{-1}(t) C(t) \left(1 + \frac{\varepsilon r^2}{4}\right)^{-2} (dx^2 + dy^2 + dz^2),$$

becomes as follows:

$$\tilde{G} = -dw^2 + R^2(w) \left(1 + \frac{\varepsilon r^2}{4}\right)^{-2} (dx^2 + dy^2 + dz^2),$$

where  $R^2(w) = \Psi^{-1}(t)C(t)$ . The induced metric of  $\tilde{G}$  on a hyperplane  $\mathbf{H}_w \subset \mathbf{M} \subset \mathbf{R}^4$  such that

$$\mathbf{H}_w = \{(w, x, y, z) \in \mathbf{M} \mid w = \text{const.}\} \hookrightarrow_i \mathbf{M}$$

is given as follows:

$$\begin{aligned} i^*(\tilde{G}) &= R^2 \left(1 + \frac{\varepsilon r^2}{4}\right)^{-2} (dx^2 + dy^2 + dz^2) \\ &= \left(1 + \frac{\varepsilon \tilde{r}^2}{4R^2}\right)^{-2} (d\tilde{x}^2 + d\tilde{y}^2 + d\tilde{z}^2), \end{aligned}$$

where  $R = R(w)$ ,  $\tilde{x} = Rx$ ,  $\tilde{y} = Ry$ ,  $\tilde{z} = Rz$ ,  $\tilde{r}^2 = \tilde{x}^2 + \tilde{y}^2 + \tilde{z}^2$ . Since this metric is just that of a sphere with a radius  $R = R(w)$  for  $\varepsilon = 1$ ,  $R = R(w)$ , which can be understood as the radius of the model at  $w$ . Rewriting Theorem 1 using the variable  $w$ , we have

**Theorem 2.** *Let  $\Gamma(\Psi, G)$  be a Otsuki connection with the condition (A) which has the forms as follows:*

$$\begin{aligned} \overline{G} &= -dt^2 + C(t)D(r)(dx^2 + dy^2 + dz^2), \\ h &= h(t) \end{aligned}$$

and  $\Gamma(\Psi, G)$  be an Otsuki type i.e.  $h \neq \text{const.}$ , then the corresponding essential metric  $\tilde{G}$  and the function  $R(w)$  become as follows:

I

$$\begin{aligned} \overline{G} &= -dt^2 + \eta^2 \sinh(\vartheta(t)) \left(1 - \frac{r^2}{4}\right)^{-2} (dx^2 + dy^2 + dz^2), \\ h(t) &= \frac{\sqrt{3}}{2} \int_{\vartheta(t)}^{\infty} \frac{ds}{\sinh(s)}, \\ \tilde{G} &= -dw^2 + R^2(w) \left(1 - \frac{r^2}{4}\right)^{-2} (dx^2 + dy^2 + dz^2), \\ R^2(w) &= \eta^2 \exp \left( + \int_{\vartheta(t)}^{\infty} \frac{ds}{\sinh(s)} \right) \sinh(\vartheta(t)), \end{aligned}$$

where  $w(t) = \int_0^t \Psi^{-\frac{1}{2}}(s)ds = \int_0^t ds \exp \left( - \int_{\vartheta(s)}^{\infty} \frac{du}{\sinh(u)} \right)$  and  $\vartheta(t)$  is the inverse function of  $t(\vartheta) = \frac{1}{2}\eta \int_0^{\vartheta} \sinh^{\frac{1}{2}}(s)ds$ .

## II

$$\begin{aligned}
\overline{G} &= -dt^2 + \eta^2 \sinh(\vartheta(t)) \left(1 - \frac{r^2}{4}\right)^{-2} (dx^2 + dy^2 + dz^2), \\
h(t) &= -\frac{\sqrt{3}}{2} \int_{\vartheta(t)}^{\infty} \frac{ds}{\sinh(s)}, \\
\tilde{G} &= -dw^2 + R^2(w) \left(1 - \frac{r^2}{4}\right)^{-2} (dx^2 + dy^2 + dz^2), \\
R^2(w) &= \eta^2 \exp\left(-\int_{\vartheta(t)}^{\infty} \frac{ds}{\sinh(s)}\right) \sinh(\vartheta(t)),
\end{aligned}$$

where  $w(t) = \int_0^t \Psi^{-\frac{1}{2}}(s) ds = \int_0^t ds \exp\left(+\int_{\vartheta(s)}^{\infty} \frac{du}{\sinh(u)}\right)$  and  $\vartheta(t)$  is the inverse function of  $t(\vartheta) = \frac{1}{2}\eta \int_0^{\vartheta} \sinh^{\frac{1}{2}}(s) ds$ .

## III

$$\begin{aligned}
\overline{G} &= -dt^2 + \sqrt{3}\eta t^{\frac{2}{3}}(dx^2 + dy^2 + dz^2), \\
h(t) &= \frac{1}{\sqrt{3}} \log(t), \\
\tilde{G} &= -dw^2 + (3\eta^2)^{\frac{2}{3}}(dx^2 + dy^2 + dz^2), \\
R^2(w) &= (3\eta^2)^{\frac{2}{3}} = \text{const.},
\end{aligned}$$

where  $w(t) = \int_0^t \Psi^{-\frac{1}{2}}(s) ds = \frac{3}{2}t^{\frac{2}{3}}$ .

## IV

$$\begin{aligned}
\overline{G} &= -dt^2 + (3\eta^2)^{\frac{2}{3}} t^{\frac{2}{3}}(dx^2 + dy^2 + dz^2), \\
h(t) &= -\frac{1}{\sqrt{3}} \log(t), \\
\tilde{G} &= -dw^2 + \frac{4}{3}(3\eta^2)^{\frac{2}{3}} w(dx^2 + dy^2 + dz^2), \\
R^2(w) &= \frac{4}{3}(3\eta^2)^{\frac{2}{3}} w,
\end{aligned}$$

where  $w(t) = \int_0^t \Psi^{-\frac{1}{2}}(s) ds = \frac{3}{4}t^{\frac{4}{3}}$ .

## V

$$\begin{aligned}
\overline{G} &= -dt^2 + \eta^2 \sin(\vartheta(t)) \left(1 + \frac{r^2}{4}\right)^{-2} (dx^2 + dy^2 + dz^2), \\
h(t) &= \frac{\sqrt{3}}{2} \int_{\vartheta(t)}^{\frac{\pi}{2}} \frac{ds}{\sin(s)},
\end{aligned}$$

$$\begin{aligned}\tilde{G} &= -dw^2 + R^2(w) \left(1 + \frac{r^2}{4}\right)^{-2} (dx^2 + dy^2 + dz^2), \\ R^2(w) &= \eta^2 \exp\left(+ \int_{\vartheta(t)}^{\frac{\pi}{2}} \frac{ds}{\sin(s)}\right) \sin(\vartheta(t)),\end{aligned}$$

where  $w(t) = \int_0^t \Psi^{-\frac{1}{2}}(s) ds = \int_0^t ds \exp\left(- \int_{\vartheta(s)}^{\frac{\pi}{2}} \frac{du}{\sin(u)}\right)$  and  $\vartheta(t)$  is the inverse function of  $t(\vartheta) = \frac{1}{2}\eta \int_0^\vartheta \sin^{\frac{1}{2}}(s) ds$ .

VI

$$\begin{aligned}\overline{G} &= -dt^2 + \eta^2 \sin(\vartheta(t)) \left(1 + \frac{r^2}{4}\right)^{-2} (dx^2 + dy^2 + dz^2), \\ h(t) &= -\frac{\sqrt{3}}{2} \int_{\vartheta(t)}^{\frac{\pi}{2}} \frac{ds}{\sin(s)}, \\ \tilde{G} &= -dw^2 + R^2(w) \left(1 + \frac{r^2}{4}\right)^{-2} (dx^2 + dy^2 + dz^2), \\ R^2(w) &= \eta^2 \exp\left(- \int_{\vartheta(t)}^{\frac{\pi}{2}} \frac{ds}{\sin(s)}\right) \sinh(\vartheta(t)),\end{aligned}$$

where  $w(t) = \int_0^t \Psi^{-\frac{1}{2}}(s) ds = \int_0^t ds \exp\left(+ \int_{\vartheta(s)}^{\frac{\pi}{2}} \frac{du}{\sin(u)}\right)$  and  $\vartheta(t)$  is the inverse function of  $t(\vartheta) = \frac{1}{2}\eta \int_0^\vartheta \sin^{\frac{1}{2}}(s) ds$ .

The functions  $R(w)$  in Theorem 2, which are measured by the variables  $w$ , have some elementary properties. Especially for type I in Theorem 2, we have

**Lemma 4.** *The range of  $w$  becomes  $0 \leq w < +\infty$  and there exists positive constants  $\alpha, \beta$  such that*

1.

$$\lim_{w \rightarrow +\infty} R(w) = \alpha.$$

2.

$$\frac{1}{\beta} \leq \lim_{w \rightarrow +\infty} \frac{R(w)}{w^2} \leq \beta.$$

3.

$$\frac{dR(w)}{dw} > 0$$

for any  $0 < w < +\infty$ .

4.

$$\lim_{w \rightarrow 0} \frac{dR(w)}{dw} = 0.$$

*Proof.* Since

$$(19) \quad s \leq \sinh(s) \leq (e + e^{-1})s,$$

$$(20) \quad \left( \frac{1 - e^{-1}}{2} \right) e^s \leq \sinh(s) \leq \frac{1}{2} e^s$$

for any  $0 \leq s \leq 1$ ,  $1 \leq s < +\infty$  respectively, we have

$$(21) \quad \left( \frac{1}{\vartheta(t)} \right)^{\frac{1}{e+e^{-1}}} \leq \exp \left( \int_{\vartheta(t)}^1 \frac{ds}{\sinh(s)} \right) \leq \frac{1}{\vartheta(t)}$$

for any  $0 \leq \vartheta(t) \leq 1$  and

$$(22) \quad \exp(2e^{-\vartheta(t)}) \leq \exp \left( \int_{\vartheta(t)}^{\infty} \frac{ds}{\sinh(s)} \right) \leq \exp \left( \left( \frac{2}{1 - e^{-1}} \right) e^{-\vartheta(t)} \right)$$

for any  $1 \leq \vartheta(t) < +\infty$ . By (19), (20) and an explicit form of  $w(t)$ :

$$(23) \quad w(t) = \frac{1}{2} \eta \int_0^{\vartheta(t)} d\xi \sinh^{\frac{1}{2}}(\xi) \exp \left( \frac{1}{2} \int_{\xi}^{\infty} \frac{ds}{\sinh(s)} \right),$$

there exist  $0 < \lambda_1 < \delta_1$  such that

$$(24) \quad \lambda_1 \xi^{\frac{1}{2} \left( 1 - \frac{1}{e+e^{-1}} \right)} \leq \sinh^{\frac{1}{2}}(\xi) \exp \left( \frac{1}{2} \int_{\xi}^1 \frac{ds}{\sinh(s)} \right) \leq \delta_1$$

for any  $0 \leq \xi \leq 1$  and by (20) and (22), there exist  $0 < \lambda_2 < \delta_2$  such that

$$(25) \quad \lambda_2 e^{\frac{\xi}{2}} \leq \sinh^{\frac{1}{2}}(\xi) \exp \left( \frac{1}{2} \int_{\xi}^{\infty} \frac{ds}{\sinh(s)} \right) \leq \delta_2 e^{\frac{\xi}{2}}$$

for any  $1 \leq \xi < +\infty$ . Using (23)  $\sim$  (25) and

$$\frac{dw}{dt} = \Psi^{-\frac{1}{2}}(t) = \exp \left( -\frac{1}{2} \int_{\vartheta(t)}^{\infty} \frac{ds}{\sinh(s)} \right),$$

we have  $\frac{dw}{dt} > 0$  for any  $0 \leq t < +\infty$ ,  $\lim_{t \rightarrow +0} w(t) = 0$  and  $\lim_{t \rightarrow +\infty} w(t) = +\infty$ . Under these preparations, we will prove  $1 \sim 4$ . By (24), (25) and the explicit form such that

$$(26) \quad R^2(w) = \eta^2 \sinh(\vartheta(t)) \exp \left( + \int_{\vartheta(t)}^{\infty} \frac{ds}{\sinh(s)} \right),$$



there exist  $\lambda_3, \delta_3 > 0$  such that

$$(27) \quad \eta^2((\lambda_2)^2 e^\vartheta + \lambda_3) \leq R^2(w) \leq \eta^2((\delta_2)^2 e^\vartheta + \delta_3)$$

for any  $1 \leq \vartheta < +\infty$ . On the other hand by (23)  $\sim$  (25), there exist  $\lambda_4, \delta_4 > 0$  such that

$$(28) \quad \eta\left(\lambda_2 e^{\frac{\vartheta}{2}} + \lambda_4\right) \leq w(t) \leq \eta\left(\delta_2 e^{\frac{\vartheta}{2}} + \delta_4\right)$$

for any  $0 \leq t < +\infty$ . By (26)  $\sim$  (28), we have

$$\lim_{w \rightarrow +\infty} R(w) = \eta\sqrt{\mu_1}, \quad \frac{\lambda_2}{\delta_2} \leq \lim_{w \rightarrow +\infty} \frac{R(w)}{w^2} \leq \frac{\delta_2}{\lambda_2},$$

where  $\mu_1 = \lim_{\vartheta \rightarrow +0} \sinh(\vartheta) \exp\left(\int_\vartheta^\infty \frac{ds}{\sinh(s)}\right)$ . Using an equality:

$$\frac{dR(w)}{dw} = \frac{1}{\sinh(\vartheta)} \{\cosh(\vartheta) - 1\} \exp\left(\frac{1}{2} \int_\vartheta^\infty \frac{ds}{\sinh(s)}\right),$$

we have  $\frac{dR(w)}{dw} > 0$  for any  $0 < w < +\infty$  and  $\lim_{w \rightarrow +0} \frac{dR(w)}{dw} = 0$ .

Next we discuss the functions  $R(w)$  of type V in Theorem 2.

**Lemma 5.** *For the type V in Theorem 2, there exist  $\delta, \nu > 0$  such that*

1.  $\frac{dR(w)}{dw} < 0$  for any  $0 < w < \nu$ ,
2.  $\lim_{w \rightarrow +0} \frac{dR(w)}{dw} = 0$ ,
3.  $\lim_{w \rightarrow \nu-0} \frac{dR(w)}{dw} = 0$ ,
4.  $\lim_{w \rightarrow +0} R(w) = \delta$ ,
5.  $\lim_{w \rightarrow \nu-0} R(w) = 0$ .

*Proof.* Since

$$(29) \quad \frac{2}{\pi}s \leq \sin(s) \leq s,$$

$$(30) \quad \frac{2}{\pi}(\pi - s) \leq \sinh(s) \leq \pi - s$$

for any  $0 \leq s \leq \frac{\pi}{2}$ ,  $\frac{\pi}{2} \leq s \leq \pi$  respectively, we have

$$(31) \quad \frac{\pi}{2\vartheta} \leq \exp\left(\int_0^{\frac{\pi}{2}} \frac{ds}{\sin(s)}\right) \leq \left(\frac{\pi}{2\vartheta}\right)^{\frac{\pi}{2}}$$

for any  $0 \leq \vartheta \leq \frac{\pi}{2}$  and

$$(32) \quad \left\{ \frac{2}{\pi}(\pi - \vartheta) \right\}^{\frac{\pi}{2}} \leq \exp \left( \int_{\vartheta}^{\frac{\pi}{2}} \frac{ds}{\sin(s)} \right) \leq \frac{2}{\pi}(\pi - \vartheta)$$

for any  $\frac{\pi}{2} \leq \vartheta \leq \pi$ . By (29), (31) and an explicit form of  $w(t)$  such that

$$(33) \quad w(t) = \frac{1}{2}\eta \int_0^{\vartheta} d\xi \sin^{\frac{1}{2}}(\xi) \exp \left( \frac{1}{2} \int_{\xi}^{\frac{\pi}{2}} \frac{ds}{\sin(s)} \right),$$

we have

$$(34) \quad 1 \leq \sin^{\frac{1}{2}}(\xi) \exp \left( \frac{1}{2} \int_{\xi}^{\frac{\pi}{2}} \frac{ds}{\sin(s)} \right) \leq \left( \frac{\pi}{2} \right)^{\frac{\pi}{4}} \left( \frac{1}{\xi} \right)^{\frac{\pi-2}{4}}$$

for any  $0 < \xi \leq \frac{\pi}{2}$  and by (30) and (32), we have

$$(35) \quad \left\{ \frac{\pi}{2}(\pi - \xi) \right\}^{\frac{\pi+2}{4}} \leq \sin^{\frac{1}{2}}(\xi) \exp \left( \frac{1}{2} \int_{\xi}^{\frac{\pi}{2}} \frac{ds}{\sin(s)} \right) \leq \sqrt{\frac{2}{\pi}}(\pi - \xi)$$

for any  $\frac{\pi}{2} \leq \xi < \pi$ . Using the explicit form of  $\vartheta(t)$ , (33)  $\sim$  (35) and

$$\frac{dw}{dt} = \Psi^{-\frac{1}{2}}(t) = \exp \left( -\frac{1}{2} \int_{\vartheta}^{\frac{\pi}{2}} \frac{ds}{\sin(s)} \right),$$

we have  $\frac{dw}{dt} > 0$  for any  $0 < \vartheta < \pi$ ,  $\lim_{\vartheta \rightarrow +0} w(t) = 0$  and  $\lim_{\vartheta \rightarrow \pi-0} w(t) = \nu < +\infty$ , where

$$\nu = \frac{1}{2}\eta \int_0^{\pi} d\xi \sin^{\frac{1}{2}}(\xi) \exp \left( \int_{\xi}^{\frac{\pi}{2}} \frac{ds}{\sin(s)} \right).$$

Under these preparations we will prove  $1 \sim 5$ . By (33)  $\sim$  (35) and the formula:

$$R^2(w) = \eta^2 \sin(\vartheta) \exp \left( \int_{\vartheta}^{\frac{\pi}{2}} \frac{ds}{\sin(s)} \right),$$

we have

$$(36) \quad \frac{dR(w)}{dw} = \left( \frac{\cos(\vartheta) - 1}{\sin(\vartheta)} \right) \exp \left( \frac{1}{2} \int_{\vartheta}^{\frac{\pi}{2}} \frac{ds}{\sin(s)} \right)$$

The right side of (36) is negative on  $0 < w < \nu$  and tends to zero when  $\vartheta \rightarrow +0$  i.e.  $w \rightarrow +0$ , so is a bounded function on  $0 \leq w \leq \nu_1$ , where  $\nu_1$  is a small positive number. Thus  $R(w)$  is a bounded function on  $0 \leq w \leq \nu$  and has the following properties:

$$\frac{dR(w)}{dw} < 0 \text{ for any } 0 < w < \nu,$$

$$\lim_{w \rightarrow +0} R(w) = \eta\sqrt{\lambda_1} \equiv \delta < +\infty,$$

$$\lim_{w \rightarrow \nu-0} R(w) = 0, \quad \lim_{w \rightarrow +0} \frac{dR(w)}{dw} = 0,$$

$$\lim_{w \rightarrow \nu-0} \frac{dR(w)}{dw} = -\infty,$$

where

$$\lambda_1 = \lim_{\vartheta \rightarrow +0} \sin(\vartheta) \exp\left(\int_{\vartheta}^{\frac{\pi}{2}} \frac{ds}{\sin(s)}\right) < +\infty.$$

Regarding properties of the functions  $R(w)$ , the other cases in Theorem 2 are trivial or almost the same as Lemma 4 or Lemma 5. Now we have the following

**Theorem 3.** *The functions  $R(w)$  in Theorem 2, which are measured by the variables  $w$ , have the following properties:*

*I The range of  $w$  becomes  $0 \leq w < +\infty$  and there exist  $\alpha, \beta > 0$  such that*

1.  $\lim_{w \rightarrow +0} R(w) = \alpha,$
2.  $\frac{1}{\beta} \leq \lim_{w \rightarrow +\infty} \frac{R(w)}{w^2} \leq \beta,$
3.  $\frac{dR(w)}{dw} > 0$  for any  $0 < w < +\infty,$
4.  $\lim_{w \rightarrow +0} \frac{dR(w)}{dw} = 0.$

*II The range of  $w$  becomes  $0 \leq w < +\infty$  and there exists  $\delta > 0$  such that*

1.  $\lim_{w \rightarrow +0} R(w) = 0,$
2.  $\frac{1}{\delta} \leq \lim_{w \rightarrow +\infty} \frac{R(w)}{w^2} \leq \delta,$
3.  $\frac{dR(w)}{dw} > 0$  for any  $0 < w < +\infty,$
4.  $\lim_{w \rightarrow +0} \frac{dR(w)}{dw} = +\infty.$

*III  $R(w) = \text{const.}$  . Thus, this case is trivial.*

*IV  $R(w) = \text{const.}\sqrt{w}$ . Thus, this case is trivial.*

*V There exist  $\delta, \nu > 0$  such that*

1.  $R(w)$  is defined on  $0 \leq w \leq \nu,$
2.  $\frac{dR(w)}{dw} < 0$  for any  $0 < w < \nu,$
3.  $\lim_{w \rightarrow +0} \frac{dR(w)}{dw} = 0,$

4.  $\lim_{w \rightarrow \nu-0} \frac{dR(w)}{dw} = -\infty,$
5.  $\lim_{w \rightarrow +0} R(w) = \delta,$
6.  $\lim_{w \rightarrow \nu-0} R(w) = 0.$

VI The functions  $R(w)$  of these models are the same as  $R(\nu - w)$  in V.

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